

SA's Leading Past Year

Exam Paper Portal



You have Downloaded, yet Another Great
Resource to assist you with your Studies 😊

Thank You for Supporting SA Exam Papers

Your Leading Past Year Exam Paper Resource Portal

Visit us @ www.saexampapers.co.za



SA EXAM
PAPERS



basic education

Department:
Basic Education
REPUBLIC OF SOUTH AFRICA

NATIONAL SENIOR CERTIFICATE

GRADE 12

ELECTRICAL TECHNOLOGY: POWER SYSTEMS

NOVEMBER 2019

MARKS: 200

TIME: 3 hours

**This question paper consists of 14 pages, a 2-page formula sheet and
1 answer sheet.**

INSTRUCTIONS AND INFORMATION

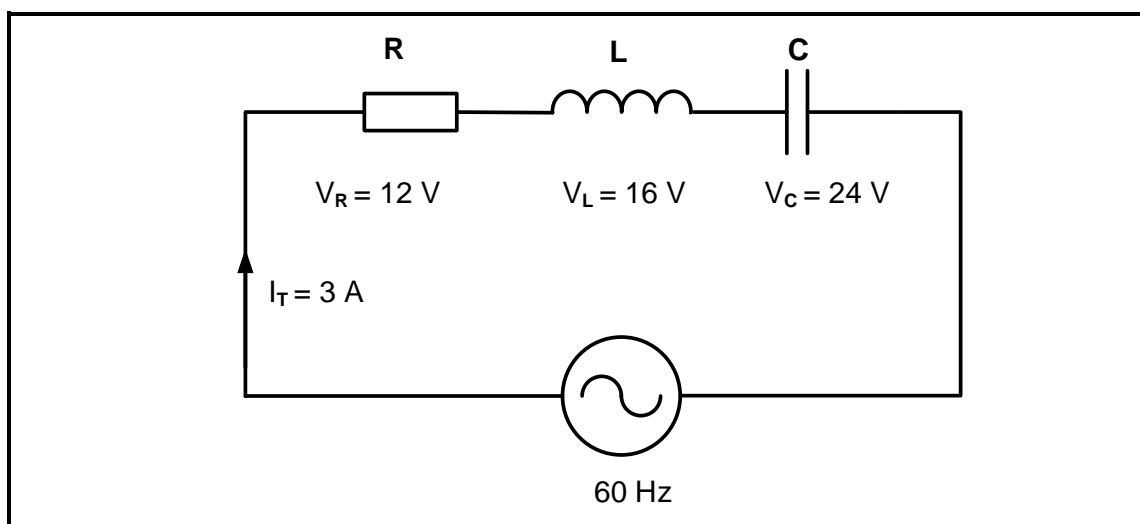
1. This question paper consists of SIX questions.
2. Answer ALL the questions.
3. Answer QUESTION 2.3.4 on the attached ANSWER SHEET.
4. Write your CENTRE NUMBER and EXAMINATION NUMBER on the ANSWER SHEET and hand it in with your ANSWER BOOK, whether you have used it or not.
5. Sketches and diagrams must be large, neat and FULLY LABELLED.
6. Show ALL calculations and round off answers correctly to TWO decimal places.
7. Number the answers correctly according to the numbering system used in this question paper.
8. You may use a non-programmable calculator.
9. Calculations must include:
 - 9.1 Formulae and manipulations where needed
 - 9.2 Correct replacement of values
 - 9.3 Correct answer and relevant units where applicable
10. A formula sheet is attached at the end of this question paper.
11. Write neatly and legibly.

QUESTION 1: OCCUPATIONAL HEALTH AND SAFETY

- 1.1 Describe how *teamwork* improves work ethics. (2)
- 1.2 With reference to the Occupational Health and Safety Act, 1993 (Act 85 of 1993):
- 1.2.1 State TWO purposes of the Occupational Health and Safety Act, 1993 (Act 85 of 1993). (2)
- 1.2.2 Define the term *workplace*. (2)
- 1.3 An employer has a duty to report on occupational health and safety and related matters. Name ONE person they should inform when:
- 1.3.1 The allocated task is hazardous (1)
- 1.3.2 A major incident occurs (1)
- 1.4 State TWO general emergency procedures to be followed when the emergency siren is sounded at school. (2)
- [10]**

QUESTION 2: RLC CIRCUITS

- 2.1 Define the following with reference to RLC circuits:
- 2.1.1 Power factor (2)
- 2.1.2 Q-factor of an inductor in a resonant circuit (2)
- 2.2 State TWO applications of RLC circuits. (2)
- 2.3 FIGURE 2.3 below shows an RLC series circuit. Answer the questions that follow.

**FIGURE 2.3: RLC SERIES CIRCUIT**

Given:

$$\begin{aligned} I_T &= 3 \text{ A} \\ V_R &= 12 \text{ V} \\ V_L &= 16 \text{ V} \\ V_C &= 24 \text{ V} \\ f &= 60 \text{ Hz} \end{aligned}$$

- 2.3.1 Calculate the total voltage of the supply. (3)
- 2.3.2 Calculate the value of the inductive reactance. (3)
- 2.3.3 State if the circuit is capacitive or inductive. Motivate your answer. (2)
- 2.3.4 Complete the phasor diagram on the ANSWER SHEET for QUESTION 2.3.4 and show the direction of rotation. (4)
- 2.3.5 Describe how an increase in impedance, while keeping the resistance constant, will affect the phase angle and the power factor. (2)

- 2.4 FIGURE 2.4 below shows an RLC parallel circuit consisting of a $20\ \Omega$ resistor, an inductor with an inductive reactance of $30\ \Omega$ and a capacitor with a capacitive reactance of $40\ \Omega$, all connected across a $120\text{ V}/60\text{ Hz}$ supply. Answer the questions that follow.

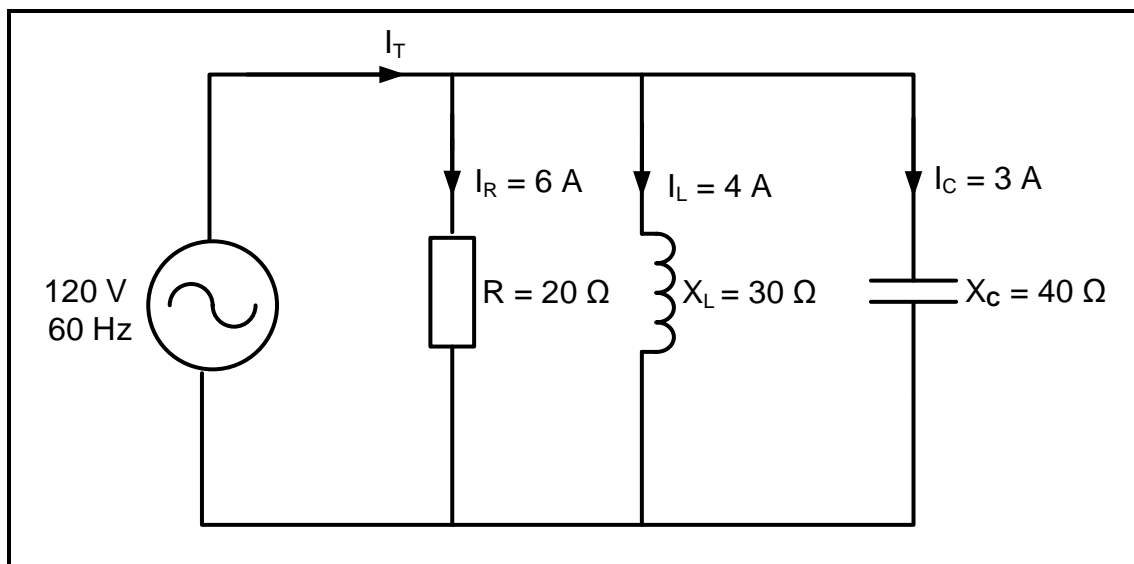


FIGURE 2.4: RLC PARALLEL CIRCUIT

Given:

$$\begin{aligned} R &= 20\ \Omega \\ X_L &= 30\ \Omega \\ X_C &= 40\ \Omega \\ V_T &= 120\text{ V} \\ f &= 60\text{ Hz} \end{aligned}$$

- 2.4.1 Calculate the total current in the circuit. (3)
- 2.4.2 Calculate the phase angle. (3)
- 2.4.3 State whether the phase angle is leading or lagging. Motivate your answer. (2)

- 2.5 FIGURE 2.5 below shows an RLC series resonant circuit which consists of a $12\ \Omega$ resistor, an inductor with an inductive reactance of $50\ \Omega$ and a variable capacitor, all connected across a $120\text{ V}/2\text{ kHz}$ supply. Answer the questions that follow.

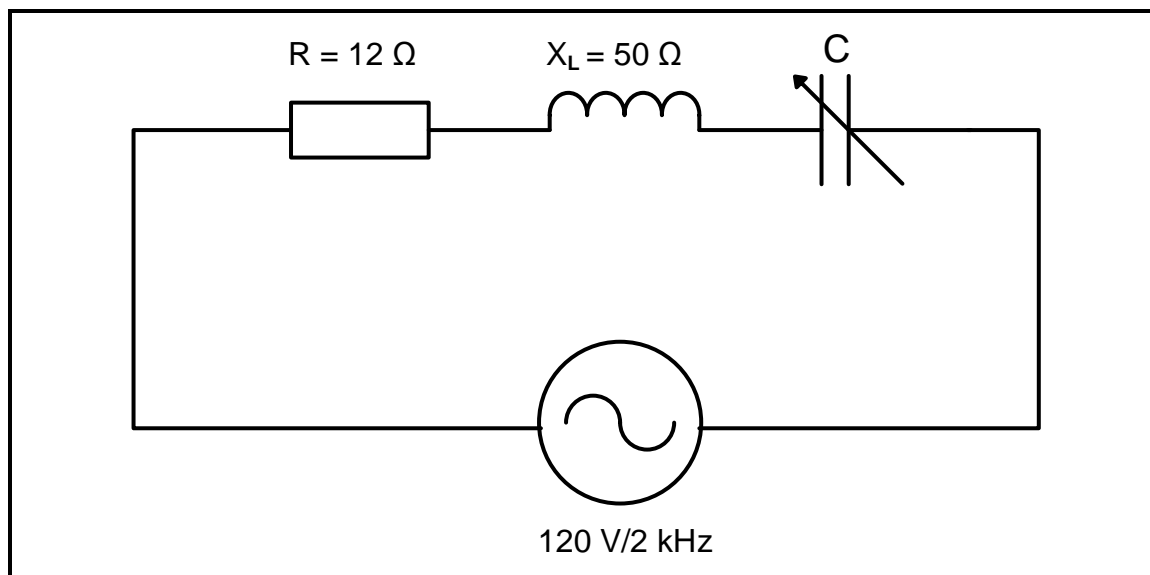


FIGURE 2.5: RLC SERIES RESONANT CIRCUIT

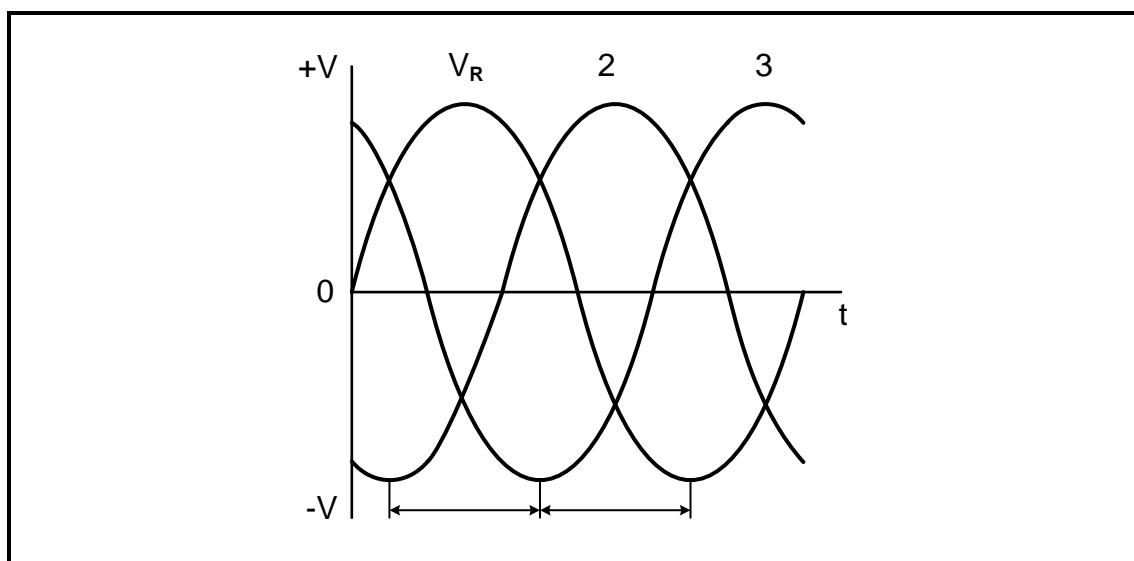
Given:

$$\begin{aligned}V_T &= 120\text{ V} \\f &= 2\text{ kHz} \\R &= 12\ \Omega \\X_L &= 50\ \Omega\end{aligned}$$

- 2.5.1 Calculate the value of **C** when the circuit resonates at 2 kHz. (4)
- 2.5.2 Calculate the value of the current in the circuit. (4)
- 2.5.3 State how current will be affected if the value of the resistance is doubled. (1)
- 2.5.4 List THREE characteristics of an RLC series circuit at resonance. (3)
- [40]**

QUESTION 3: THREE-PHASE AC GENERATION

- 3.1 List THREE advantages of power factor improvement for the consumer. (3)
- 3.2 Explain why the power distribution to consumers is connected in star. (2)
- 3.3 State the difference between a *wattmeter* and a *kilowatt-hour meter*. (2)
- 3.4 State the purpose of the following:
- 3.4.1 National power grid (1)
- 3.4.2 Eskom's national control centres (1)
- 3.5 Refer to FIGURE 3.5 below and answer the questions that follow.

**FIGURE 3.5: THREE-PHASE VOLTAGE WAVEFORM**

- 3.5.1 Label the generated voltage waveforms marked **2** and **3** according to the universally adopted sequence.
NOTE: Take V_R as reference. (2)
- 3.5.2 Name the phase displacement between the three waveforms generated in FIGURE 3.5. (1)
- 3.6 A 380 V three-phase, star-connected AC motor has an output power of 25 kW and it operates at a lagging power factor of 0,87. The efficiency of the motor is 85%.
- Given:
- $V_L = 380 \text{ V}$
 $\eta = 85\%$
 $\cos \theta = 0,87 \text{ lagging}$
 $P_{\text{out}} = 25 \text{ kW}$
- Calculate the:
- 3.6.1 Input power (3)
- 3.6.2 Line current (3)
- 3.6.3 Phase current (2)

3.7 Refer to FIGURE 3.7 below and answer the questions that follow.

Given:

$$P_1 = 14 \text{ kW}$$

$$P_2 = 18 \text{ kW}$$

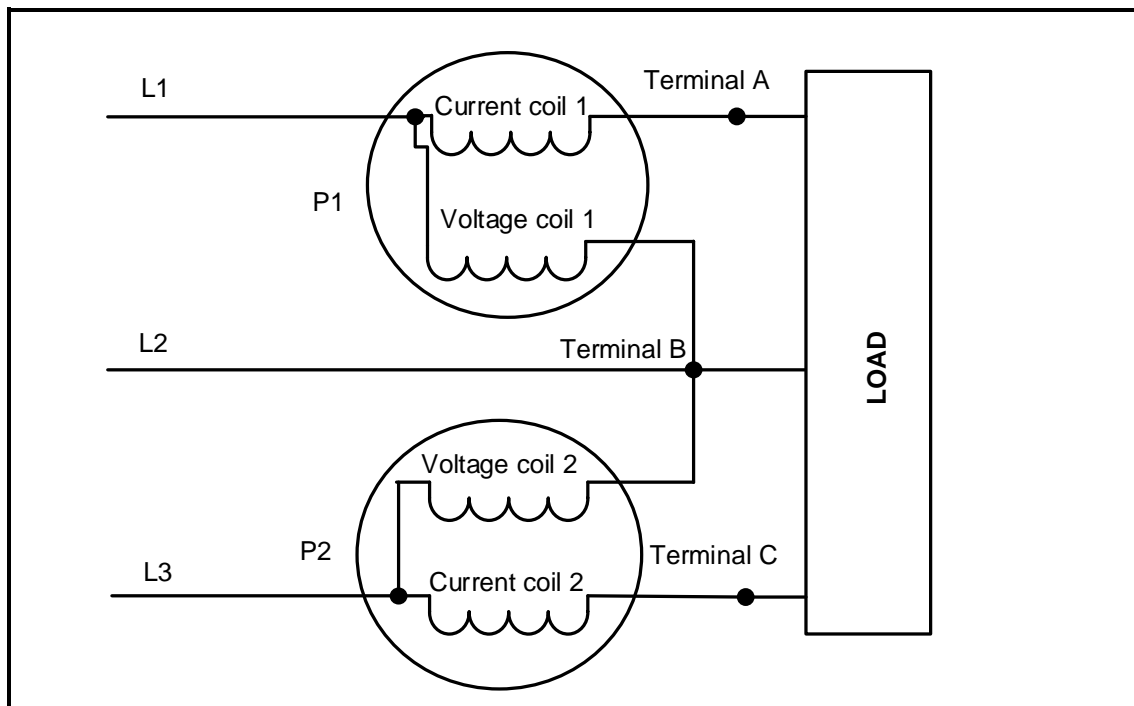


FIGURE 3.7

3.7.1 Identify the method used in FIGURE 3.7 to measure the power to the load. (1)

3.7.2 Calculate the total power used by the load. (3)

3.7.3 Calculate the power factor of the system. (3)

3.8 A delta-connected three-phase load is supplied by a 20 kVA generator with a phase voltage of 220 V. The power factor of the load is given as 0,85 lagging. Calculate the line current at full load.

Given:

$$S = 20 \text{ kVA}$$

$$V_{PH} = 220 \text{ V}$$

$$PF = 0,85$$

(3)
[30]

QUESTION 4: THREE-PHASE TRANSFORMERS

- 4.1 List THREE external conditions that may cause transformer failure. (3)
- 4.2 Explain what would happen if an earth fault occurs in one of the three phases of a protected transformer. (3)
- 4.3 Describe how an increase in the load would affect the magneto motive force in the primary windings. (3)
- 4.4 Name TWO types of cooling methods for a dry transformer. (2)
- 4.5 State why the output power of a transformer is slightly less than the input power. (1)
- 4.6 Describe the construction of a three-phase core-type transformer. (3)
- 4.7 A star-delta connected transformer has 600 turns in the primary windings and 80 turns in the secondary windings. The transformer is connected to a 6 kV supply.

Given:

$$N_P = 600 \text{ turns}$$

$$N_S = 80 \text{ turns}$$

$$V_{L(P)} = 6 \text{ kV}$$

Calculate the:

- 4.7.1 Turns ratio (3)
- 4.7.2 Primary phase voltage (3)
- 4.7.3 Secondary phase voltage (3)
- 4.7.4 Secondary line voltage (2)
- 4.8 With reference to Faraday's law, describe how mutual induction occurs in a transformer. (4)
- [30]**

- 5.5 A 16 kW three-phase star-connected motor with 12 poles, is connected across a 380 V/50 Hz supply and draws a phase current of 29 A with a power factor of 0,85.

Given:

Number of poles	=	12
$\cos \theta$	=	0,85
P_{out}	=	16 kW
V_L	=	380 V
I_{PH}	=	29 A
f	=	50 Hz

Calculate the:

- | | | |
|-------|---|-------------|
| 5.5.1 | Apparent power | (3) |
| 5.5.2 | Synchronous speed | (5) |
| 5.5.3 | Percentage slip if the rotor speed is 1 400 r/min | (3) |
| | | [30] |

QUESTION 6: PROGRAMMABLE LOGIC CONTROLLERS (PLCs)

6.1 With reference to PLCs:

6.1.1 Name the system used for automated machine control for industrial production before PLCs were developed. (1)

6.1.2 State THREE health and safety issues to consider, other than anti-surge protection, when working with PLC equipment and installations. (3)

6.2 Explain the term *software* with reference to the operation of a PLC. (3)

6.3 Explain why it is important to install anti-surge protection when working with PLCs. (2)

6.4 With reference to the input devices of PLCs:

6.4.1 Define the term *sensor*. (2)

6.4.2 List THREE types of sensors other than a level sensor. (3)

6.4.3 State an application of a level sensor. (1)

6.4.4 Describe the function of an analogue device. (2)

6.5 Refer to FIGURE 6.5 below and answer the questions that follow.

Input A	Input B	Output (F)
0	0	0
0	1	1
1	0	1
1	1	1

FIGURE 6.5: TRUTH TABLE

6.5.1 Draw the logic gate symbol that this truth table represents. (3)

6.5.2 Draw the ladder logic diagram that this truth table represents. (3)

6.5.3 Write the logic function of FIGURE 6.5. (2)

6.6 FIGURE 6.6 below shows a PLC logic program with a time delay of 10 seconds. Answer the questions that follow:

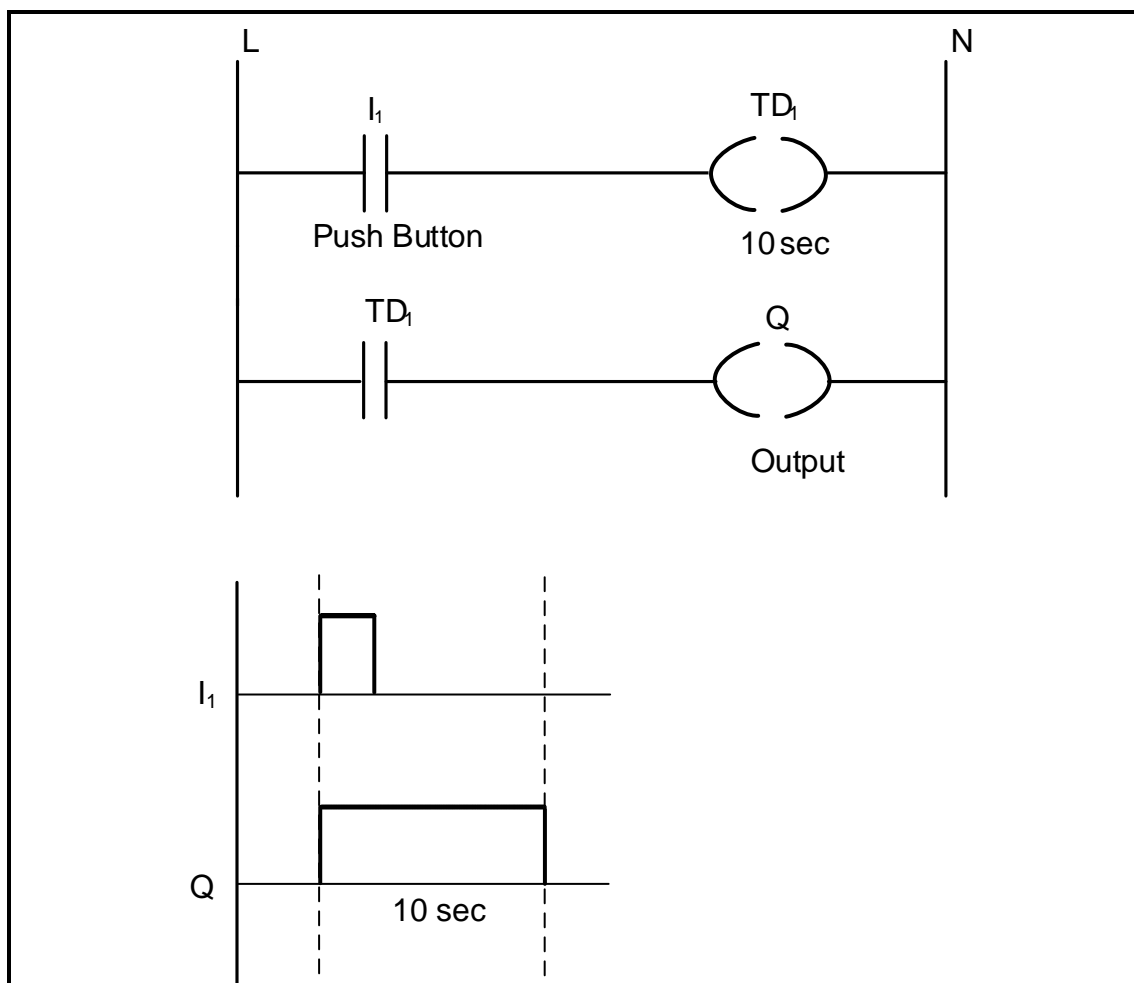


FIGURE 6.6: TIME-DELAY PLC LOGIC PROGRAM

- 6.6.1 State whether the logic program uses an ON-delay timer contact or an OFF-delay timer contact. (1)
- 6.6.2 Describe the sequential operation of the logic program when the push button (I_1) is pressed. (5)

- 6.7 Draw a ladder logic diagram that will execute the same function as the control circuit in FIGURE 6.7 below.

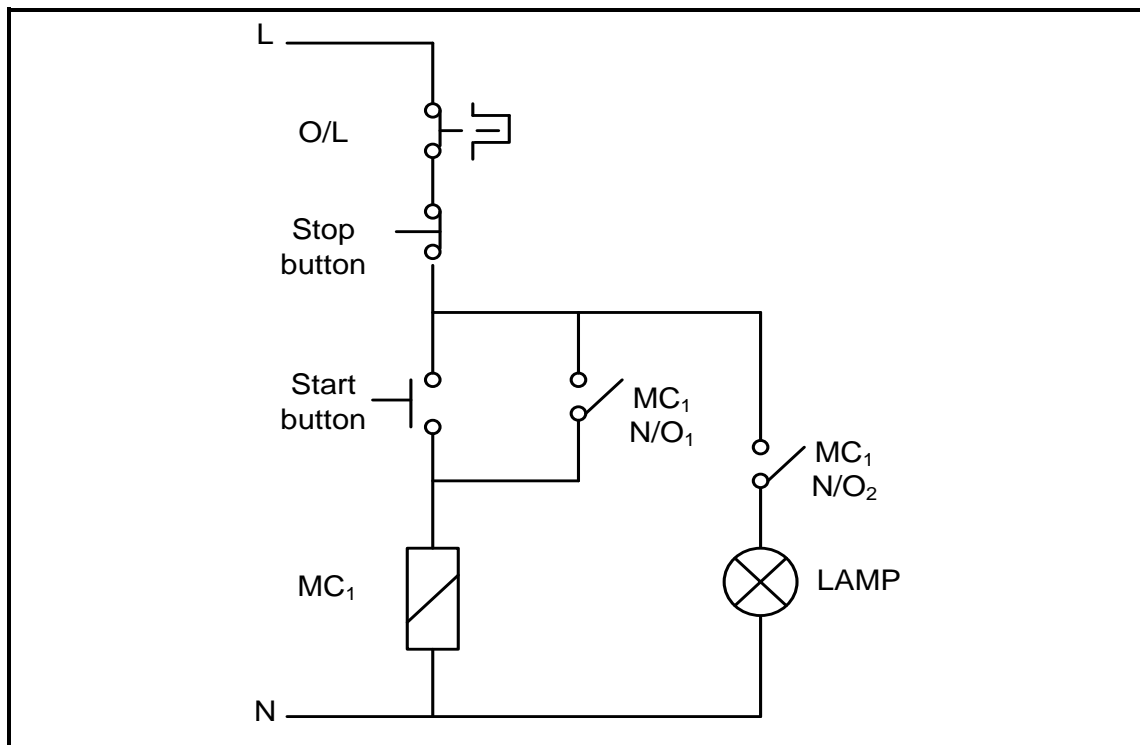


FIGURE 6.7: CONTROL CIRCUIT

(7)

- 6.8 FIGURE 6.8 below shows a variable frequency drive (VFD) circuit. Study the circuit and answer the questions that follow:

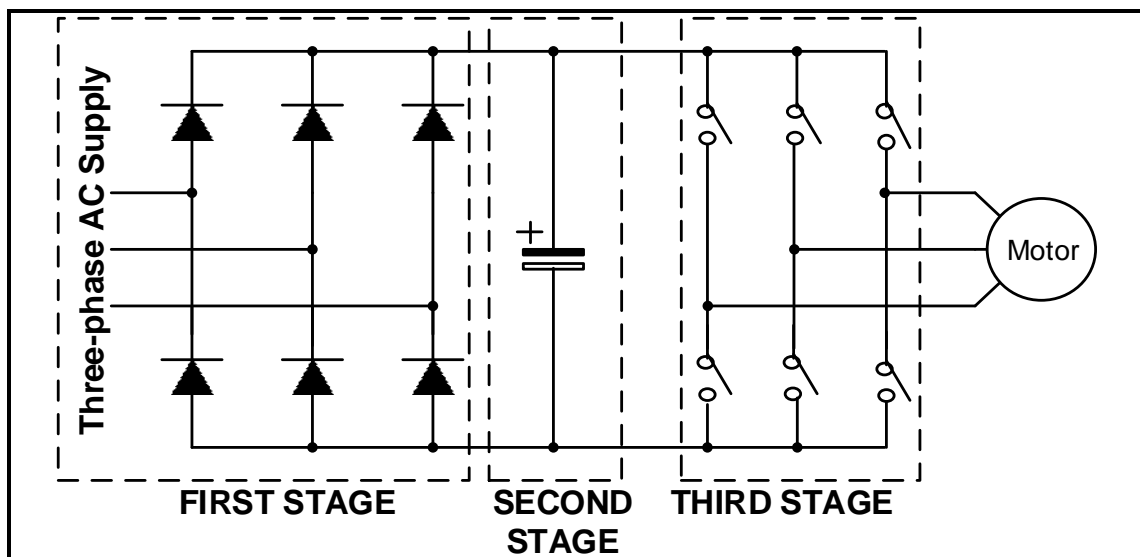


FIGURE 6.8: VARIABLE FREQUENCY DRIVE (VFD) CIRCUIT

- 6.8.1 Describe the purpose of the first stage of the VFD circuit. (2)
- 6.8.2 Explain how speed control is achieved by using the switches in the third stage. (2)
- 6.8.3 Explain how the output waveform and the frequency of the supply will be affected if the switches remain 'ON' for a longer period. (2)

6.9 With reference to the use of the VFD to control the speed of a motor, answer the following questions:

6.9.1 State THREE production advantages for industries and manufacturers when using a VFD to control the speed of a motor. (3)

6.9.2 Name ONE application of a VFD. (1)

6.9.3 List THREE VFD methods that can be used to control the speed of a motor. (3)

6.10 With reference to the regenerative braking process:

6.10.1 Give THREE examples where regenerative braking is applied other than in lifts. (3)

6.10.2 Explain how regenerative braking is achieved. (2)

6.11 FIGURE 6.11 below shows the characteristic curve of speed versus torque when the VFD is used to control the speed of a three-phase induction motor. Study the characteristic curve and answer the questions that follow.

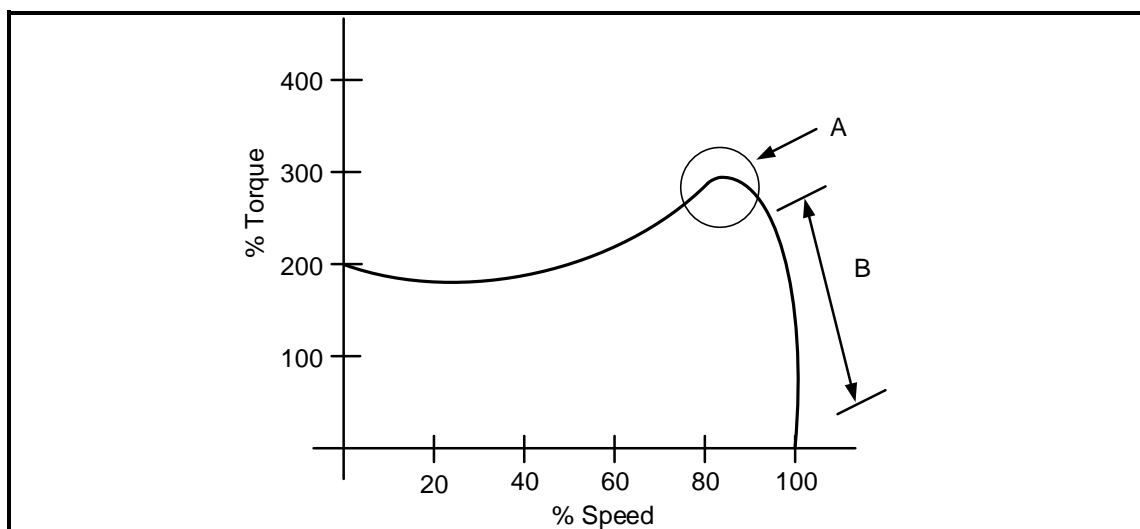


FIGURE 6.11: SPEED-TORQUE CHARACTERISTIC CURVE

6.11.1 Name region A. (1)

6.11.2 Describe the *start up and run profile* of the induction motor in FIGURE 6.11. (3)
[60]

TOTAL: 200

FORMULA SHEET	
RLC CIRCUITS	THREE-PHASE AC GENERATION
$P = V \times I \times \cos \theta$ $X_L = 2\pi fL$ $X_C = \frac{1}{2\pi fC}$ $f_r = \frac{1}{2\pi\sqrt{LC}}$ $BW = \frac{f_r}{Q}$ SERIES $V_R = IR$ $V_L = I X_L$ $V_C = I X_C$ $I_T = \frac{V_T}{Z}$ OR $I_T = I_R = I_C = I_L$ $Z = \sqrt{R^2 + (X_L - X_C)^2}$ $V_T = \sqrt{V_R^2 + (V_L - V_C)^2}$ OR $V_T = IZ$ $\cos \theta = \frac{R}{Z}$ OR $\cos \theta = \frac{V_R}{V_T}$ $Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_T} = \frac{V_C}{V_T} = \frac{1}{R} \sqrt{\frac{L}{C}}$ PARALLEL $V_T = V_R = V_L = V_C$ $I_R = \frac{V_T}{R}$ $I_C = \frac{V_T}{X_C}$ $I_L = \frac{V_T}{X_L}$ $I_T = \sqrt{I_R^2 + (I_L - I_C)^2}$ $Z = \frac{V_T}{I_T}$ $\cos \theta = \frac{I_R}{I_T}$ $Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{I_L}{I_T} = \frac{I_C}{I_T} = \frac{1}{R} \sqrt{\frac{L}{C}}$	STAR $V_L = \sqrt{3} V_{PH}$ $V_{PH} = I_{PH} \times Z_{PH}$ $I_L = I_{PH}$ DELTA $V_L = V_{PH}$ $V_{PH} = I_{PH} \times Z_{PH}$ $I_L = \sqrt{3} I_F$ POWER $S (P_{app}) = \sqrt{3} \times V_L \times I_L$ $Q (P_r) = \sqrt{3} \times V_L \times I_L \times \sin \theta$ $P = \sqrt{3} \times V_L \times I_L \cos \theta$ $\cos \theta = \frac{P}{S}$ EFFICIENCY $\eta = \frac{\text{output power}}{\text{input power}} \times 100\%$ TWO-WATTMETER METHOD $P_T = P_1 + P_2$ $\tan \theta = \sqrt{3} \left(\frac{P_1 - P_2}{P_1 + P_2} \right)$ THREE-WATTMETER METHOD $P_T = P_1 + P_2 + P_3$

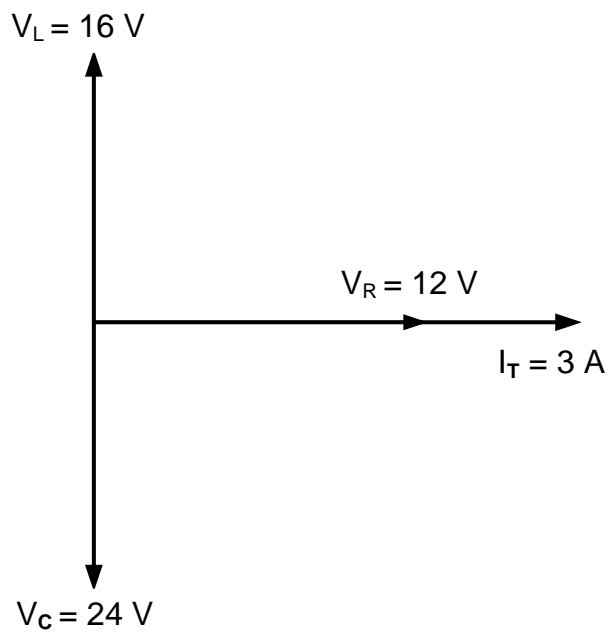
THREE-PHASE TRANSFORMERS	THREE-PHASE MOTORS AND STARTERS
STAR $V_L = \sqrt{3} V_{PH}$ and $I_L = I_{PH}$ DELTA $I_L = \sqrt{3} I_{PH}$ and $V_L = V_{PH}$ POWER $S (P_{app}) = \sqrt{3} \times V_L \times I_L$ $Q (P_r) = \sqrt{3} \times V_L \times I_L \times \sin \theta$ $P = \sqrt{3} \times V_L \times I_L \cos \theta$ $\cos \theta = \frac{P}{S}$ $\frac{V_{ph(p)}}{V_{ph(s)}} = \frac{N_p}{N_s} = \frac{I_{ph(s)}}{I_{ph(p)}}$ <p>Transformer ratio (TR)</p> $TR = \frac{N_p}{N_s}$	STAR $V_L = \sqrt{3} V_{PH}$ and $I_L = I_{PH}$ DELTA $I_L = \sqrt{3} I_{PH}$ and $V_L = V_{PH}$ POWER $S (P_{app}) = \sqrt{3} \times V_L \times I_L$ $Q (P_r) = \sqrt{3} \times V_L \times I_L \times \sin \theta$ $P = \sqrt{3} \times V_L \times I_L \cos \theta$ $\cos \theta = \frac{P}{S}$ EFFICIENCY $\eta = \frac{\text{output power}}{\text{input power}} \times 100\%$ $n_s = \frac{60 \times f}{p}$ $\% \text{ slip} = \frac{n_s - n_r}{n_s} \times 100$ $\text{Per Unit Slip} = \frac{n_s - n_r}{n_s}$ $\text{Slip} = n_s - n_r$

CENTRE NUMBER:								
----------------	--	--	--	--	--	--	--	--

EXAMINATION NUMBER:													
---------------------	--	--	--	--	--	--	--	--	--	--	--	--	--

ANSWER SHEET

2.3.4

Transfer mark to
answer book

MOD

FIGURE 2.3.4**(4)**